## Thomas Cheng Li

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## EDUCATION

## Weston High School GPA: 3.96/4.0 ACT: 35

AP Calculus BC, AP Physics C: Mechanics and E&M, AP Chemistry, AP Computer Science, AP World History, AP U.S. History, AP Psychology, AP Biology, AP European History, AP Statistics, AP Spanish, AP English

## PROJECTS

## Functional Annotation of Variants Online Resource (FAVOR) Mar. 2023 - Present

Prof. Xihong Lin, Harvard University

- Aggregated large genomic data (9 billion single nucleotide variants, 80 million observed genetic insertions/deletions, and 160 columns of variant annotations) into FAVOR [\(https://favor.genohub.org\)](https://favor.genohub.org), an online database widely used by medical researchers to connect disease traits with human genetic information.
- Conceptualized and developed a natural language interpretation model (FAVOR-GPT) to easily query and extract relevant information from the database and generate insights, reducing the barrier of entry and making the database more accessible to researchers worldwide.
- Presented research at The Impact of Genomic Variation on Function (IGVF) Consortium and published a first-author paper in peer-reviewed *[Bioinformatics Advances](https://doi.org/10.1093/bioadv/vbae143)*, 2024, vbae143.

## Sign Language Recognition **Sign Language Recognition** Jan. 2021 - Aug. 2023

[https://github.com/hsteven-archive/sign](https://github.com/hsteven-archive/sign_lang) lang

- Worked with another high-schooler to build a computer vision program using Python to recognize and translate American Sign Language (ASL) into English in real-time.
- The model can be used to automatically caption and translate videos for accessibility or to teach ASL more effectively, with the goal of improving communication for the deaf and hard of hearing.
- Wrote a co-first-author paper published in the Research Archive of Rising Scholars (2023).

## PUBLICATIONS

## FAVOR-GPT: A Natural Language Interface to Genomic Annotations

Thomas Cheng Li, Hufeng Zhou, Vineet Verma, Xiangru Tang, Yanjun Shao, Bioinformatics Advances (2024) Eric Van Buren, Zhiping Weng, Shamil R Sunyaev, Mark Gerstein, Xihong Lin [doi.org/10.1093/bioadv/vbae143](https://doi.org/10.1093/bioadv/vbae143)

## Sign Language Recognition from Video using Geometrical

and Transfer Learning Techniques Research Archive of Rising Scholars (2023)

David Chen and Thomas Cheng Li (Co-first authors) [doi.org/10.58445/rars.486](https://doi.org/10.58445/rars.486)

## EXTRACURRICULARS

## Princeton University Laboratory Learning Program (LLP) Summer 2024

Utilizing LLMs to find information on Wastewater Treatment Facilities, with Prof. Jason Ren

- 6% acceptance rate summer internship experience to work under accomplished Princeton professor.
- Built program that is able to automatically gather publically available information for wastewater treatment plants and other environmentally related facilities.
- Expanded the capabilities of state of the art LLMs for answering environmental engineering questions using vector databases.

## Stony Brook University Simons Summer Research Program (SSRP) Jul. 1 - Aug. 9, 2024 Characterizing Machine Learning Methods for Medical Time Series Diagnosis, with Dr. Alisa Yurovsky

- 5% acceptance rate summer research program to do bioinformatics research at Stony Brook University.
- Trained time series transformer classification models in order to detect Acute Kidney Failure using Electronic Health Records from the Trinetx database.
- Analyzed and tested different data imputation methods for patient data to increase model performances.

- Best Research Project (2nd place) Award for \$1,500 cash prize (team) 2023 AAASE Princeton University Summer Academy
- National Merit Scholarship Semifinalist (received the maximum score of 1520 on the PSAT) 2023

• Trained Generative Adversarial Networks to generate synthetic EHR data that balances underrepresented patient groups or conditions, reducing bias and improving the model's fairness and generalization across diverse populations.

## **Physics Club, Weston High School Sep. 2022 - Present Sep. 2022 - Present**

Co-President

- Founded high school Physics Club by gathering 25 interested student signatures, finding a faculty advisor, and presenting idea to administrators for approval.
- Organized club meetings every other week to practice and discuss challenging physics problems, tutor Freshman students for Honors Physics.

## Cybersecurity Club, Weston High School Channel Controller and Controller Controller and Oct. 2021 - Present

Captain

- Competed in Cyberpatriot's National Youth Cyber Defense Competition, held by the Air & Space Forces Association where thousands of students from around the US compete in securing compromised Windows/Linux systems; Won the Platinum Division 1st Place State Award and the Platinum Division Semifinalist Award.
- Competed in the Cyberstart program where 42,402 students competed to solve challenging security-related problems; Won the National Semifinalist award.
- Elected team captain and organized weekly meetings for ∼10 student members to practice cybersecurity competition problems, published 132-page book Digital Literacy 101 on [amazon.com/dp/B0DBSWX8ZL.](https://www.amazon.com/dp/B0DBSWX8ZL)
- Interned part-time for cybersecurity firm BG Networks, providing security solutions against ransomware.

## Students for Environmental Action (SEA) group Oct. 2022 - Present

Co-President

- Volunteered 2 hours every week to support local sustainability by planting trees, building forest trails, and encouraging recycling (bought and set up 5 of the first recycling trash cans in school history).
- Lobbied and testified in front of state congress over climate bills (e.g. Air Quality EJ bill), engaged in local town sustainability decisions as a student representative on the sustainability committee, and joined the Massachusetts Youth Climate Coalition (MYCC), aiming to tackle air quality control, voting transparency, and climate-friendly building renovations. A member of [Town of Weston's Sustainability Committee.](https://www.westonma.gov/1296/Sustainability-Committee)
- Elected Vice-President and organized weekly meetings, volunteering opportunities, and other initiatives amongst the ∼7 consistent members. Built and maintained its website [seaweston.org](https://seaweston.org)

## Visitor Volunteer at NewBridge on the Charles Senior Home Apr. 2024 - Present

AWARDS

United States of America Computing Olympiad (USACO) Gold (testing for Platinum in Dec.) 2024

Certificate of Distinction (placed [133rd in the world out of 3,077 participants\)](https://drive.google.com/file/d/1mHFGJ9fniQtK28Xqn_kI5eAQ8gRnoWfg/view?usp=sharing) in Sir Isaac Newton Exam of Physics, organized by the Department of Physics & Astronomy, University of Waterloo 2024

## Cyberpatriot's National Youth Cyber Defense Competition 2023

Platinum Division 1st Place State Award, Platinum Division Semifinalist Award, Gold Division 1st Place Award.

- The nation's largest cyber defense contest (over 3,000 schools participating with 5 members per school on average), held by the Air & Space Forces Association.
- Received a [letter of congratulation from Massachusetts State Representative Alice](https://drive.google.com/file/d/14URIy0e_LPgKDskD6gQVhVy2xa43vR8t/view?usp=sharing) Peisch.

## 3rd Place Award at the [Massachusetts Science & Engineering Fair \(MSEF\)](https://scifair.com/wp-content/uploads/2024/04/2024-MSEF-High-School-Award-Winners-1.pdf) 2024

Analysis and Machine Learning Modeling of Spatial Data to Identify Asthma Hotspots in Massachusetts

# <span id="page-2-0"></span>Databases and ontologies

# **FAVOR-GPT: a generative natural language interface to whole genome variant functional annotations**

**Thomas Cheng Li1,2,†, Hufeng Zhou1,†, Vineet Verma<sup>1</sup> , Xiangru Tang<sup>3</sup> , Yanjun Shao<sup>3</sup> , Eric Van Buren<sup>1</sup> , Zhiping Weng<sup>4</sup> , Mark Gerstein5,6, Benjamin Neale7,8, Shamil R. Sunyaev8,9 , Xihong Lin1,8,10,**�

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#### **Abstract**

**Motivation:** Functional Annotation of genomic Variants Online Resources (FAVOR) offers multi-faceted, whole genome variant functional annotations, which is essential for Whole Genome and Exome Sequencing (WGS/WES) analysis and the functional prioritization of disease-associated variants. A versatile chatbot designed to facilitate informative interpretation and interactive, user-centric summary of the whole genome variant functional annotation data in the FAVOR database is needed.

**Results:** We have developed FAVOR-GPT, a generative natural language interface powered by integrating large language models (LLMs) and FAVOR. It is developed based on the Retrieval Augmented Generation (RAG) approach, and complements the original FAVOR portal, enhancing usability for users, especially those without specialized expertise. FAVOR-GPT simplifies raw annotations by providing interpretable explanations and result summaries in response to the user's prompt. It shows high accuracy when cross-referencing with the FAVOR database, underscoring the robustness of the retrieval framework.

**Availability and implementation:** Researchers can access FAVOR-GPT at FAVOR's main website [\(https://favor.genohub.org\)](https://favor.genohub.org).

## **1 Introduction**

Multi-faceted variant functional annotation plays a pivotal role in the analysis and interpretation of the findings of array-based Genome-Wide Association Studies (GWAS) and WGS studies [\(Watanabe](#page-5-0) *et al.* 2017, Li *[et al.](#page-5-0)* 2020, [Quick](#page-5-0) *et al.* 2020). Examples of large scale WGS studies include the Trans-Omics Precision Medicine (TOPMed) Program, UK Biobank, and *All of Us* [\(Sudlow](#page-5-0) *et al.* 2015, [Karczewski](#page-5-0) *et al.* 2020, [Taliun](#page-5-0) *et al.*  [2021](#page-5-0)). Variant function annotations can be used for functional fine mapping [\(Kichaev](#page-5-0) *et al.* 2014, [Schaid](#page-5-0) *et al.* 2018), partitioned heritability [\(Finucane](#page-5-0) *et al.* 2015), polygenic risk scores (PRSs; [Marquez-Luna](#page-5-0) *et al.* 2021), and rare variant association analysis of WGS studies (Li *[et al.](#page-5-0)* 2022).

The Functional Annotation of Variants Online Resources (FAVOR) database and portal ([Zhou](#page-5-0) *et al.* 2023) provides an open access comprehensive online platform for functional annotations of genetic variants, genomic regions and genes across the whole genome. FAVOR efficiently summarizes and visualizes multi-faceted functional annotation data of all possible (approximately nine billion) single nucleotide variants (SNVs), and insertion and deletion variants (Indels) observed in large-scale genome sequencing studies, such as TOPMed, covering the entire human genome. It enables quick and convenient querying at variant, gene, and region levels. FAVOR integrates variant functional information from diverse sources to elucidate the functional attributes of variants, and assists the prioritization of potential causal variants influencing human phenotypes. However, effectively utilizing FAVOR necessitates a certain level of prior specialized knowledge and background. Users are required to possess a fundamental understanding of different annotation metrics and the specific genes or variants they wish to query,

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<span id="page-3-0"></span>in addition to adhering to the correct input formats. Second, there are various terms and scores that users may need to refer to the FAVOR documentation to understand ([Zhou](#page-5-0) *et al.*  [2023\)](#page-5-0). Third, the queried results on the FAVOR portal are static with raw annotation results, precluding interactive calculation of summary statistics of interest.

There is a significant need to develop a user-friendly tool to respond to natural language queries, and provide results in an interactive format that are easy to understand without prior knowledge. This will help bridge the gap in accessibility and usability of variant functional annotations in genetics and genomic research. There are increasing interests in leveraging Large Language Models (LLMs; [Touvron](#page-5-0) *et al.* 2023), such as Chat-GPT, GPT-4 [\(OpenAI 2023](#page-5-0)) and LLaMA [\(Touvron](#page-5-0) *et al.* 2023) in biomedical applications. This transformative technology offers attractive artificial intelligence capabilities. For example, GPT-4 have shown proficiency and intelligence in human interactions, achieved through instruction tuning and feedbackbased training. These potentials have ignited significant interest and excitement within the scientific research community toward LLMs [\(Sallam 2023](#page-5-0)). In the open-source world, LLaMA has become increasingly popular [\(Touvron](#page-5-0) *et al.* 2023). LLaMA3.1's performance is on par with GPT-4. This advancement shows great potential for researchers seeking to enhance customization. Recently, VarChat (Paoli *et al.* 2024) was introduced to integrate chatbot-based variant search with the publications from PubMed to generate summaries. It is, however, limited to the small subset of variants documented in the published literature. It lacks the ability to query for multi-faceted functional annotations of any variant (SNV) across the human genome, and fails to provide functional information for a large number of variants in WGS studies.

In this paper, we introduce FAVOR-GPT, an interactive tool that leverages knowledge-guided LLMs to enhance the user experience interacting with the FAVOR database. Compared to the competitive products, we selected the ChatGPT API from OpenAI for following reasons. First, it offers high-quality and contextually relevant responses, while boasting rapid response times, ensuring users receive prompt replies to their queries. Second, ChatGPT provides extensive tools available in the JavaScript ecosystem, and its support for function calling makes it an ideal candidate for adopting the Retrieval-Augmented Generation (RAG) approach. It allows to integrate external knowledge sources and our inhouse FAVOR APIs seamlessly into the language model's generation framework, enhancing the accuracy and relevance of the responses. Third, opting for ChatGPT APIs eliminates the need to run a local language model, and reduces the amount of additional responsibilities and complexities, such as hardware requirements, model fine-tuning, and maintenance. ChatGPT offers a more straightforward setup process, enabling us to focus on building our applications rather than managing the underlying infrastructure.

FAVOR-GPT exhibits the ability to understand user inputs in natural language and improve user experience in navigating the FAVOR database and portal. Its inherent flexibility allows it to accommodate a wide range of input formats, ensuring that queries are properly understood. In addition to retrieve query results from the FAVOR database, FAVOR-GPT has several attractive features. When presenting raw annotation results and values, it enriches these findings with relevant background introduction and leverages the natural language explanations generated by LLM (ChatGPT). It also generates

summary statistics calculated using the FAVOR database in response to prompts. This integrative approach significantly improves the understanding of functional annotation results, making the utilization of FAVOR easier for researchers. FAVOR-GPT introduces a practical approach to integrating LLMs specifically tailored for variants functional annotation, without the substantial resource requirements of pretraining or fine-tuning large models.

#### **2 Methods**

FAVOR-GPT was developed with flexibility, resource efficiency, and adaptability in mind. It was made to combine the documentation information with the annotations from the FAVOR database.

FAVOR-GPT is implemented based on the Retrieval Augmented Generation (RAG; Guo *[et al.](#page-5-0)* 2023) approach, an AI framework that enhances responses based on an external textual knowledge source. In this case, based on the text query of the user, FAVOR-GPT allows ChatGPT to retrieve textual data in real time from the FAVOR database automatically via the FAVOR API, and thus grounding the LLM on the information from the FAVOR database and documentation and related sources for generating reliable and detailed responses, see [Fig. 1.](#page-4-0) For all gene-related information, FAVOR-GPT utilizes a vector database based on Weaviate to fetch information relevant to the query. Gene information is separated into categories, such as pathway, function, identification, and embedded separately using the "text-embedding-3-small" vectorizer model from OpenAI.

To enhance user comprehension of the annotation results, FAVOR-GPT employs an in-depth analysis of relevant documentation, aligning it with the values obtained from the queries. FAVOR-GPT then employs the ChatGPT APIs to generate natural language explanations of the annotation results from the FAVOR API queries, presenting the information in a format that is easy to understand. Further, FAVOR-GPT can conduct data analysis in response to various queries, such as calculating the number of pathogenic variants in BRCA1. FAVOR-GPT also allows for the user to easily cross-verify the data given in FAVOR-GPT with the database itself. All FAVOR-GPT and FAVOR API documentation can be found at [https://docs.genohub.org/.](https://docs.genohub.org/)

The workflow of FAVOR-GPT is illustrated in [Fig. 1.](#page-4-0) By harnessing the natural language generation capabilities of Chat-GPT, FAVOR-GPT ensures that users receive not only raw annotation data but also contextual and coherent explanations of multi-faceted functional annotations of variants, genes and genomic regions. The current version of FAVOR-GPT is implemented using the TypeScript programming language [\(Bierman](#page-5-0) *[et al.](#page-5-0)* 2014) with the Vercel.AI SDK ([Grammel](#page-5-0) *et al.* 2023), with a deliberate effort to smoothly integrate it into the existing FAVOR user interface which build on the React/Next.js framework. FAVOR-GPT's presence in the user interface is marked by a clickable floating button placed on the FAVOR website. The source code for the site can be found at [https://github.com/](https://github.com/zhouhufeng/FAVOR-GPT) [zhouhufeng/FAVOR-GPT](https://github.com/zhouhufeng/FAVOR-GPT).

We conducted benchmark testing on FAVOR-GPT by randomly selecting contexts from the vector database and using GPT-4 to create 100 questions based on specific categories like gene function or location. These questions are then answered by both FAVOR-GPT and GPT-4. The answers are assessed based on two metrics: *relevance* and *accuracy*.

<span id="page-4-0"></span>

Figure 1. Graphical representation of the FAVOR-GPT workflow. The FAVOR-GPT workflow demonstrates how it converts natural language into structured query syntax and then interprets the query results into clear and fluid natural language.

Relevance measures how well the model's response addresses the question, with scores of 1 (answer directly pertains to the question), 0.5 (answer tangentially pertains to the question), and 0 (answer does not address the question at all). Accuracy measures how factually correct the answer is, with scores of 1 (completely correct), 0.5 (has mistaken but is largely correct), and 0 (factually incorrect). These scores are determined by a GPT-4 model with access to all the necessary context. To compare the model result, we had a plain GPT-4 model answer the same questions and be evaluated similarly.

## **3 Results**

FAVOR-GPT can make any query to satisfy the text inputs. These queries include gene-level functional annotation queries, gene-based variant queries, and variant-specific functional annotation queries. [Supplementary Figure S1](https://academic.oup.com/bioinformaticsadvancesarticle-lookup/doi/10.1093/bioadv/vbae143#supplementary-data) shows examples of queries and responses. Users can ask free-form questions like "What is the function of the gene APOE?" and "What is the function of rs942096275?" FAVOR-GPT will provide comprehensive easy-to-understand answers.

FAVOR-GPT is equipped to address computational queries such as analyzing and summarizing data, for instance, genelevel and region-level variant calculations using the FAVOR database. Examples of such computational quires include "What is the range for TP53 gene?," "How many variants in APOE?," "How many pathogenic variants in BRCA1?," "How many loss of function variants in APOE?," "How many variants in APOE with aPC Epigenetics Repressed *>* 20?." These responses are shown in [Supplementary Figure S2 and Table S1](https://academic.oup.com/bioinformaticsadvancesarticle-lookup/doi/10.1093/bioadv/vbae143#supplementary-data). These gene-level variant calculations are performed using the TOPMed Bravo variant list, which contains observed variants in TOPMed-BRAVO and is part of the FAVOR database. This is achieved through the FAVOR API, which is designed to handle such specific queries. The FAVOR web interface offers limited gene and region level summary statistics. In contrast, FAVOR-GPT is much more flexible, enabling users to calculate a wide range of customized summary statistics based on their specific queries.

The evaluation of FAVOR-GPT shows good performance in providing variant functional annotation information. FAVOR-GPT had a relevance score of 0.865 and an accuracy score of 0.85, whereas the regular GPT-4 model had a relevance score of 0.5 and an accuracy score of 0.595 (All the examples are placed in [Supplementary Table S3](https://academic.oup.com/bioinformaticsadvancesarticle-lookup/doi/10.1093/bioadv/vbae143#supplementary-data)). In many cases, the GPT-4 model resorted to saying that it did not know the answer to the question, such as "How many pathogenic variants does BRCA1 have?" which raised the accuracy score to be decently high as "I don't know." Although the scores show that FAVOR-GPT still has room for improvement, they also show that the current RAG system by integrating the high quality whole genome variant annotation database FAVOR significantly improves generelated and variant-related queries and calculations.

## <span id="page-5-0"></span>**4 Discussions**

We have developed FAVOR-GPT, an interactive interface that leverages Language Model APIs with the multi-faceted variant functional annotation database. It furnishes encompassing annotation results within the FAVOR ecosystem, ensuring that users have access to comprehensive knowledge-guided information and explanations. FAVOR-GPT exhibits relevance and accuracy in interpreting users' natural language inputs, translating them into structured database queries, and explaining annotation results in natural language and hyperlinks of the sources. Serving as the one of the core interfaces for accessing functional annotation within FAVOR, it is also capable of performing various summary statistics calculations using the data in FAVOR.

The utilization of FAVOR-GPT enables a wider community of researchers to more easily conduct genetics and bioinformatics research. Our efforts to harness the power of Language Model APIs to enhance bioinformatics database usage will be helpful for similar developments in the field. The advent of DNN-driven LLMs represents a valuable force for a new type of interface that improves database user experience. FAVOR-GPT sets an example for navigating large and complex databases of a similar nature. By providing a model for developing and implementing intuitive, natural language-driven interfaces, FAVOR-GPT showcases an effective implementation approach for other specialized knowledge bases to broaden their reach and enhance user experience.

#### **Supplementary data**

[Supplementary data](https://academic.oup.com/bioinformaticsadvancesarticle-lookup/doi/10.1093/bioadv/vbae143#supplementary-data) are available at *Bioinformatics Advances* online.

## **Conflict of interest**

B.M.N. is on the Scientific Advisory Board of Deep Genomics, a consultant for Camp4 Therapeutics, Takeda Pharmaceutical and Biogen. S.R.S. is consultant to NGM Biopharmaceuticals and Inari agriculture. He is also on Scientific Advisory Board of Veritas Genetics. X.L. is a consultant of AbbVie Pharmaceuticals and Verily Life Sciences. Z.W. co-founded and serves as a scientific advisor for Rgenta Inc.

#### **Funding**

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## **Data availability**

The data and software of FAVOR-GPT underlying this article are available in FAVOR database, at [https://favor.geno](https://favor.genohub.org/) [hub.org/](https://favor.genohub.org/) and source code of FAVOR-GPT can be accessed at [https://github.com/zhouhufeng/FAVOR-GPT.](https://github.com/zhouhufeng/FAVOR-GPT)

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Application Note

# AutoRecycle: Building an AI-Driven Automated Recycling Bin Using Vision Transformers

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## Abstract

Recycling is crucial for sustainability, yet current methods are error-prone. This research introduces AutoRecycle, an intelligent recycling machine designed to automate waste sorting using advanced machine learning techniques. By leveraging the RealWaste dataset and a Vision Transformer (ViT) model trained with the Self-Supervised DINO method, our system aims to enhance sorting accuracy and reduce contamination in recycling streams. We created a proof of concept physical machine that includes a high-resolution camera, a servo motor, and a ultrasonic sensor integrated with a Raspberry Pi for real-time image processing. Experimental results demonstrate that our ViT model achieves 95.16% accuracy in detailed waste classification and 98.74% accuracy in binary recyclability classification. AutoRecycle proves to be a scalable prototype that can significantly improve effective recycling rates. Video demonstration and source code can be viewed at our project website: [https://robbiebusinessacc.github.io/.](https://robbiebusinessacc.github.io/)

## 1 Introduction

A recent survey indicates that 94% of Americans support recycling, and only 35% regularly recycle, primarily due to a lack of convenient access and confusion over recyclable materials [\[1\]](#page-11-0). Current manual sorting methods are labor-intensive, prone to errors, and result in high costs and nearly 25% contamination in recycling streams[\[22\]](#page-11-1). This project aims to address these issues by developing an AI-driven automated recycling bin, AutoRecycle, which uses a Vision Transformer (ViT) model trained on the RealWaste dataset to accurately identify and sort various waste types [\[20\]](#page-11-2) [\[2\]](#page-11-3). By integrating newer machine learning techniques with hardware components, this system seeks to improve sorting efficiency and provide a scalable solution for modern recycling needs.

## 2 Literature Review

Current automated recycling mainly uses convolutional neural networks (CNNs) and support vector machines (SVM) to separate waste with accuracies of 83% and 94.8% respectively and only separated into plastic, paper, and metal [\[11\]](#page-11-4) [\[16\]](#page-11-5). Further, recycling is highly sensitive to contamination, and small amounts of wrongly recycled trash can damage the recyclability of a whole container, meaning accuracies of below 95% are not good enough for practical use [\[5\]](#page-11-6). Advancements in machine learning, particularly Vision Transformers (ViTs), offer a promising solution to these limitations by achieving high accuracy in image-based waste classification tasks [\[4\]](#page-11-7). The RealWaste dataset, with its diverse real-world waste images, is a great resource for training effective models. Unlike pristine datasets, this dataset has data from real world landfills and has enabled models like Inception V3 to reach 89.19% accuracy [\[18\]](#page-11-8)[\[20\]](#page-11-2) [\[21\]](#page-11-9).

<sup>∗</sup>Both authors contributed equally to this work.

#### 2.1 Vision Transformers

This paper distinguishes itself by integrating a Vision Transformer (ViT) model, trained with the Self-Supervised DINO method, into an automated recycling bin system using the RealWaste dataset [\[2\]](#page-11-3). Unlike traditional CNNs, which rely heavily on local feature extraction, ViTs leverage global attention mechanisms to capture long-range dependencies and contextual information more effectively. Recent literature has consistently shown the superiority of transformer-based architectures across various domains, the primary example being natural language processing models like GPT [\[13\]](#page-11-10)[\[14\]](#page-11-11). Transformers have also demonstrated state-of-the-art results in visual recognition tasks, where CNNs have traditionally dominated [\[2\]](#page-11-3) [\[9\]](#page-11-12). Additionally, vision transformers have provided a robust framework for learning joint text-and-image embeddings such as CLIP [\[12\]](#page-11-13), and they have helped account for how the human visual system develops from early sensory experience [\[10\]](#page-11-14). Because of this previous literature in this field, we were motivated to employ a ViT model, which has yielded higher accuracy compared to previous studies, including those utilizing Inception V3 [\[4\]](#page-11-7) [\[23\]](#page-11-15) [\[20\]](#page-11-2).

## 3 Methodology

On top of creating the machine learning model, we also designed and implemented the hardware necessary to physically separate waste into recyclable and non-recyclable categories.



Figure 1: Diagram demonstrating the logic design of the prototype trash can

#### 3.1 Software Design

#### 3.1.1 Data Collection and Preparation

The RealWaste dataset comprises thousands of images categorized into cardboard, food organics, glass, metal, miscellaneous trash, paper, plastic, textile trash, and vegetation classes.

Step	Description	
Data Loading	The RealWaste dataset was loaded using the fastai library [6].	
Preprocessing	<b>Cleaning:</b> Implicitly handled within the dataset loading and transforma- tion pipeline. <b>Resizing:</b> Images resized to 224x224 pixels as part of the data augmen- tation process. Normalization: Using ImageNet statistics to match the pre-trained model's input distribution [3]. <b>Augmentation:</b> Data augmentation techniques from fastai applied to create variations of training images [6].	
Data Splitting	80% of the data used for training, and 20% reserved for validation.	

Table 1: Data Preparation Steps

#### 3.1.2 Model Training

We employed a Vision Transformer (ViT) architecture for image classification tasks; specifically the ViT model trained with the Self-Supervised DINO method [\[2\]](#page-11-3). Although the pretrained checkpoint was self-supervised, we used supervised learning to further train it for our specific task.

Step	Description	
Model Initialization	ViT model (vit_base_patch16_224.dino) initialized with pre-trained weights on the ImageNet dataset [2] [4].	
<b>Custom Head</b>	Defined to attach to the ViT model, tailored to the number of waste categories.	
Learning Rate Finder	Suggested optimal learning rates for efficient training.	
Training	<b>Initial Phase:</b> 40 epochs with a learning rate slice between $1 \times 10^{-3}$ and $1 \times 10^{-1}$ . <b>Additional Phase:</b> 20 epochs with a lower learning rate range of $1 \times$ $10^{-4}$ to $1 \times 10^{-3}$ .	
Evaluation	Performance metrics include validation accuracy, precision, recall, F1 score, confusion matrix, and top losses analysis.	

Table 2: Training Process Details

#### 3.2 Hardware Design



Figure 2: Labeled images of the prototype trash can (Front image on the left - Back on the right)

#### 3.2.1 Key Components

Table 3: Key components of the AutoRecycle system

Component	Specifications	<b>Function</b>
Camera Module	High resolution, wide field of view	Captures waste images
Servo Motor	High torque, quick response	Directs items into categories
<b>Ultrasonic Sensor</b>	Accurate range and angle	Detects objects, triggers sorting
Arduino Board	Model, clock speed, I/O pins	Controls servo
Raspberry Pi	High processing power, ample memory	Runs algorithms, communicates with Arduino

#### 3.2.2 Control Logic and Software Integration

• Arduino Control Logic: Programmed to receive signals from the sensor and control the servo motor. The code is written in C++ and utilizes the Arduino IDE for deployment.

• Raspberry Pi Software Setup: Scripts are written to get live proximity information from the sensor, capture images, process them, and send control signals to the Arduino based on the machine-learning output.

## 4 Results



Figure 3: Confusion matrix of the AutoRecycle system

#### 4.1 Model Performance

The machine learning model's performance was evaluated using a confusion matrix, top losses, and validation accuracy. Specifically, the performance analysis was divided into two key categories: detailed waste classification and binary recyclability classification. The detailed waste classification involved identifying the exact category of the waste item, such as metal, paper, cardboard, etc. The ViT model demonstrated high accuracy in this task, achieving a validation accuracy rate of 95.16%. This indicates that the model is proficient in distinguishing between different types of recyclable materials, making it highly effective for precise sorting operations. For a more streamlined sorting process, the model was also evaluated on its ability to classify waste items into recyclable and non-recyclable categories. This is to mimic the real-life separation of single-stream recycling [\[7\]](#page-11-18). In this context, recyclable materials included metal, plastic, glass, paper, and cardboard, while non-recyclable materials comprised all other waste types. In this binary classification task, the model achieved an impressive validation accuracy of 98.74%.

#### 5 Discussion and Conclusion

Our prototype bin serves as a proof of concept for an automated single-stream recycling system. Compared to previous studies, which achieved lower classification accuracy rates of 94.8% and below, our ViT model's 95.16% validation accuracy in more detailed classification and 98.74% in binary classification represent a significant advancement [\[19\]](#page-11-19) [\[16\]](#page-11-5).Further, our physical prototype is a novel demonstration of how such a machine-learning model could be applied. However, limitations such as identifying a combination of different waste types remain. Future research can build on this work by expanding the dataset, adding more sensors and cameras, and scaling the system for use.

With further development, the AutoRecycle design could significantly increase recycling rates by up to 30% due to removing the fear of miss recycling from the population [\[8\]](#page-11-20) [\[1\]](#page-11-0). Additionally, the decrease in recycling errors could increase the resources recycled by 20% due to decreasing contamination [\[22\]](#page-11-1). Overall, this intelligent recycling machine represents a promising advancement in waste management, potentially improving recycling efficiency. Recycling has huge positive impacts on climate change, water quality, and pollution. Recycling by itself could reduce carbon dioxide emissions by 6 gigatons by 2050, while reducing water pollution and air pollution from paper by  $35\%$ and 74% respectively [\[15\]](#page-11-21) [\[17\]](#page-11-22).

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## Sign Language Recognition from Video using Geometrical and <sup>2</sup> Transfer Learning Techniques

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#### Abstract

 We aim to develop an American Sign Language (ASL) recognition system to bridge the communica- tion barrier for the deaf and hard-of-hearing communities. Some previous projects utilized specialized hardware, while this study focuses on purely 2-D video stream recognition due to its accessibility. In this paper, we use the őne-tuning method, which involves őne-tuning a neural network model trained on public datasets for speciőc individuals in a data-efficient manner. Challenges such as image background interference and occlusion are discussed. The algorithms are tested on teenager, adult and senior male and female hands and the accuracies are comparatively better than other previous models, with the results average testing accuracy being 96.696%.

## <sup>18</sup> 1 INTRODUCTION

 The deaf and hard-of-hearing population has faced communication barriers throughout history, leading to signiőcant challenges in their day-to-day lives. American Sign Language (ASL), a visual language used by millions of people worldwide, has become an essential means of communication for this population. However, <sup>22</sup> the majority of the general population remains unable to understand ASL, exacerbating the communication divide. In recent years, machine learning and artiőcial intelligence have demonstrated immense potential in <sup>24</sup> addressing such challenges by creating systems capable of understanding and interpreting sign language.

 The primary aim of this research project is to develop and test new ASL recognition systems, capable of identifying and interpreting sign language gestures in real time. By developing a reliable ASL recognition system, this project aims to break down communication barriers for the deaf and hard-of-hearing commu- nities, while promoting accessibility and social integration. In the long term, the successful deployment of sign language recognition systems in various applications such as education, healthcare, and public services, will contribute to creating a more inclusive and supportive society for all. While some projects have used a variety of hardware systems that normal people would not use, like special gloves, multiple cameras, etc. <sup>32</sup> We wanted to test recognition systems with a single purely 2-D video stream, with a variety of background interference, lighting and hand conditions.

<sup>34</sup> After reviewing the field, we have decided to employ two methods. The first is the 3-D Hand Geome- try(HG) method, which uses an open source library Mediapipe to identify the 3-dimensional joint positions (landmarks) of the hand. We then created a non machine learning python code which computes the ge-<sup>37</sup> ometric relations between the landmarks, and sorts the video stream into different gestures. The second method is the Transfer Learning(TL) method, which utilizes a pre-trained neural network based on stock photo data. The model is then őne tuned based on live captured video footage of a new individual user's <sub>40</sub> hand, by optimizing a small portion of the neural network weights while fixing the rest. The aim of this

<sup>41</sup> project is to compare the two methods for the purpose of detecting sign language that is effective at working <sup>42</sup> with all types of hands and environments.



Figure 1: Visualization of Mediapipe hand landmark locations based on hand joints. Labels 1-4 are along the thumb, 5-8 are along the pointer őnger, 9-12 are along the middle őnger, 13-16 are along the ring őnger, and 17-20 are along the pinky finger. In total there are 20 landmarks to represent the 3-D geometric state of the hand in any image.

## <sup>43</sup> 2 Hand Geometry

<sup>44</sup> In this section, we describe the Hand Geometry(HG) method, which recognizes ASL signs through the 3-

<sup>45</sup> D geometric relations between different joints or landmarks in the hand. This method is similar to past

<sup>46</sup> research on ASL methods, which used glove-like devices to render the hand in three dimensions and identify

<sup>47</sup> the gestures from there.[1] In contrast to these methods, our 3-D Hand Geometry method only requires 2-D

pictures and videos, which makes it more applicable to general users.

#### 2.1 Landmark Identification

 The objective of the Hand Geometry method is to utilize the Mediapipe hand landmarker library [2] which  $\mathbf{51}$  numerizes each finger joint into position values  $x, y, z$ . Each frame in a computer vision image can be **52** represented by its three RGB values such that  $F = \{ \{F_{R_i}, i = 0, ..., n \cdot m\}, \{F_{G_i}, i = 0, ..., n \cdot m\} \}, \{F_{B_i}, i = 0, ..., n \cdot m\} \}$ 53 0, ...,  $n \cdot m$  where n and m are the dimensions of the image. The set of of hand landmarks is represented <sup>54</sup> as  $L = \{L_i = (x_i, y_i, z_i), i = 0, ..., 20\}$  where each  $(x_i, y_i, z_i)$  tuple is defined by the Mediapipe model M such that

$$
(x_i, y_i, z_i) = M(F, i)
$$
\n<sup>(1)</sup>

where each of the  $xyz$  tuples represent the 3 dimensional location of the landmarks.

#### <sup>57</sup> 2.2 Landmark Geometry

Given the three dimensional position of all the landmarks in the hand, we then used a Python program which tests all the geometric relations between each landmark in order to determine the sign output. For example, 60 the orientation of the three landmarks  $L_0, L_5, L_{17}$  give the direction of the palm depending on whether  $L_0$  is  $\bullet$  the highest landmark of the three in terms of the y coordinate. Furthermore, the relation of different joints could be used to determine whether two őngers were in contact with each other or if they were inside the palm area.

```
64 def palm(self,pt):
65 # form a triangle from the key points indexed by 0, 5, 17
66 self.triangle = np.array([self.xyz[0], self.xyz[5], self.xyz[17]])
67 assert len(self.triangle) == 3
68 vecs = self.triangle - pt
69 cosines = np{\cdot}zeros((3))70 cosines[0] = np.sum(vecs[0] * vecs[1]) / (np.linalg.norm(vecs[0]) * np.linalg.norm(vecs[1]))
71 cosines[1] = np.sum(vecs[0] * vecs[2]) / (np.linalg.norm(vecs[0]) * np.linalg.norm(vecs[2]))
72 cosines[2] = np.sum(vecs[1] * vecs[2]) / (np.linalg.norm(vecs[1]) * np.linalg.norm(vecs[2]))
73 count = np.sum(cosines < 0)
74 if count >= 2:
75 return True
76 else:
77 return False
78
79 ...
80
81 def letter_M(self):
82 if self.touching(self.middle_tip,self.thumb_ip,self.accuracy):
83 if self.touching(self.index_tip,self.thumb_ip,self.accuracy):
84 if self.palm(self.pinky_tip):
85 return True
86 return False
87
88 ...
89
90 def letter_C(self):
91 if not self.palm(self.pinky_tip) and not self.palm(self.index_tip)
92 and not self.palm(self.ring_tip) and not self.palm(self.middle_tip) and
93 not self.touching(self.thumb_tip, self.middle_tip, self.accuracy):
94 if self.touching(self.pinky_tip, self.ring_tip, self.accuracy) and
95 self.touching(self.index_tip,self.middle_tip,self.accuracy):
96 if not self.palm(self.thumb_tip):
```

```
97 if self.palm_direction(self.wrist, self.index_mcp, self.pinky_mcp)[1] == "up":
98 return True
99 return False
100
```
 The above shows the Python code snippets of the 3-D HG method. A lot of "if else" statements are required to be programmed and it is quite time consuming to debug the code, but we are able to őnish it in reasonable shape.

#### 2.3 Implementation errors

 One of the challenges in using Mediapipe's hand landmarks for identifying sign language is the varying geometric tolerances for different hands. Each person has different hand sizes, shapes and colors, leading to variations in the decision statements about landmark relationships. As a result, the accuracy of identifying gestures can differ between individuals. This discrepancy poses a challenge when creating a program that aims to accurately recognize sign language across a diverse range of users. Adjusting the accuracy thresholds to accommodate various hand variations becomes crucial but also adds complexity to the implementation.

 Another source of inaccuracy when using Mediapipe's hand 3-D landmarks for sign language identiőcation is the image background interference that can affect landmark detection. The hand tracking algorithm relies on distinguishing the hand from the background, and any elements in the environment that resemble or overlap with the hand can interfere with accurate landmark labeling. For instance, if the background for the picture or video is a similar color to the user's hands, it will cause identiőcation errors where the background becomes identiőed as a hand. These background factors can introduce errors in recognizing sign language gestures, compromising the overall accuracy of the system.

 In sign language, different joints and regions of the hand are utilized to form speciőc signs or gestures. However, when performing certain signs, it is possible that some hand joints or landmarks get occluded or blocked from the camera's view. This occlusion can occur when the hand crosses over itself, when őngers overlap, or when certain hand conőgurations obscure speciőc landmarks. As a result, the missing or obscured landmarks can lead to inaccuracies in identifying the intended sign language gesture. Dealing with occlusion scenarios becomes a signiőcant challenge in leveraging Mediapipe's hand landmarks for sign language recognition, as it requires additional techniques or algorithms to handle partial or incomplete landmark information.





(a) Error Example 1 (b) Error Example 2

Figure 2: Error Example 1 shows landmark errors when joints are close together. Error Example 2 shows landmark errors with background objects identified as joints.

## <sup>126</sup> 3 Transfer Learning Method

 In this section, we describe the second methodology of recognizing ASL signs from 2-D RGB video streams. We start with brieőng the problem deőnition of ASL alphabet recognition in Section 3.1. Next we introduce the őne tuning technique applied in Section 3.3, which is a common technique in neural network based 130 deep learning. In Section 3.4, we present our software design on mobile device that assists few shots data collections on a new domain (i.e. the hand of a new user) for the purpose of model őne tuning. Related

implementation details are provided in Section 3.5.



Figure 3: The proposed ASL recognition system featuring neural network model őne tuning on mobile device. Red arrow flow: offline ASL model training pipeline using public datasets. Green arrow flow: ASL model fine tuning using individualized collected datasets. Blue arrow flow: fine tuned ASL model online inference on mobile end. Our ASL recognition model takes more than 85,000 video frames and predicts ASL letters given mobile captured video stream in 30 fps.

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#### <sup>133</sup> 3.1 Problem Definition

<sup>134</sup> The objective is to determine a single ASL letter out of 26 alphabets and 3 special characters [3] from <sup>135</sup> streamed video frames. Because some of the signatures in the alphabet such as "Z" and "J" are motion  $136$  based, the frames in computer vision's terminology are represented as a sequence X of RGB images in terms of  $X = \{x_{RGB,t}\}_{t=1}^T$ , where the length of video frames is denoted by T. The set of ASL alphabets is represented as  $Y = \{y_i, i = 1, ..., 29\}$ . Our ASL recognition problem hence can be defined as learning a 139 model  $M$  such that

$$
y_t = \mathcal{M}(x_{\text{RGB},t})
$$
\n<sup>(2)</sup>

140 where  $y_t \in Y$  given the timestamp t is the recognized ASL letter. Because the prediction of the highest <sup>141</sup> likelihood letter is the optimal one from 29 ASL characters, this problem is considered a classiőcation 142 problem, and therefore  $M$  would be a classification model with neural network weights to be optimized. 143 For all timestamps  $t = 1, ..., T$ ,  $\mathcal{M}(x)$  would represent the model ouput and  $y(x)$  would be the vector <sup>144</sup> representation of the label, with the vector value being 1 at the index where the classiőcation is correct and 145 0 everywhere else. Therefore if  $\mathcal{M}(x)$  has the highest value at the same index where  $y(x)$  is equal to 1, and <sup>146</sup> furthermore if this highest value is very positive, the model would be more accurate for that one instance.

#### <sup>147</sup> 3.2 Model Learning

<sup>148</sup> Given the classiőcation problem stated in Eq. 2, we apply a similar modeling approach with traditional <sup>149</sup> image classiőcation deep neural networks [4] in order to address object classiőcation on image domain. The <sup>150</sup> model we trained can be decomposed into the following:

$$
\mathcal{M} = \{ \mathcal{M}_{\text{B}B}, \mathcal{M}_{\text{F}C} \} \tag{3}
$$

151 where  $\mathcal{M}_{\rm BB}$  represents the backbone network layers (BB) that encode the RGB images to multi dimensional 152 features.  $\mathcal{M}_{FC}$  is a fully connected layer (FC) placed at the end of M. It maps the encoded features to the <sup>153</sup> layer of classiőcation output. The objective is to minimize the so-called cross-entropy loss[5] between the <sup>154</sup> classiőcation predictions and target:

$$
L(x,y) = \frac{\sum_{n=1}^{N} l_n}{N}
$$
\n<sup>(4)</sup>

<sup>155</sup> where

$$
l_n = -\sum_{c=1}^{C} \omega_c \log \frac{\exp(\mathcal{M}(x)_{n,c})}{\sum_{i=1}^{C} \exp(\mathcal{M}(x)_{n,i})} y(x)_{n,c}
$$
(5)

156 where  $\frac{\exp(\mathcal{M}(x)_{n,c})}{\sum_{i=1}^C \exp(\mathcal{M}(x)_{n,i})}$  is the probability predicted by the model of the label being in class c, and  $y(x)_{n,c}$ 157 is either 0 or 1 depending on whether the label is of class c.  $\omega_c$  is the individual weight for each class, which

158 is used because of the different number of appearances for each class in the training dataset. Because  $\omega_c$  is <sup>159</sup> there to counteract the training set inequality, it is a őxed value and does not change during model learning. 160 As the model at the moment is a classification model for classifying between 29 classes,  $C$  is 29.[5]

<sup>161</sup> In this work we used different optimizers, including RMSProp(RMSP), Adam, and AdamW, to obtain 162 the optimal neural network parameters for  $\mathcal{M}(x)$  that minimizes cross entropy loss.

#### <sup>163</sup> 3.3 Model Fine Tuning

 Following the learning objective defined in Eq. 4, model M can be trained by iterating through the dataset 165 points  $\{x, y(x)\}\_D$ . Evaluation of the model can be performed on the subset  $D_{sub} \in \{x, y(x)\}\_D$  which is unseen during the training. In real-world applications, ASL video frames are collected *in-the-wild* with diverse backgrounds and hand size, shape and color proőles. Those frames may fail at classiőcation for  $\frac{1}{66}$  initial M because the image data, in appearance, can be quite different from the dataset applied to model training. And as we can see in Sec. 2, these background factors can wildly affect the output results in a negative way.

<sup>171</sup> To attain a more applicable model, we apply the őne tuning technique [6]. The core strategy of őne  $_{172}$  tuning a neural network is to continue the training referring to Eq. 4 on a fixed set of layers in model M 173 while keeping the rest of layers weights unchanged. Specifically, the model weights of  $\cal{M}$  are categorized as:

$$
\{\omega, \omega \in \mathcal{M}\} = \{\omega_{\text{f}x}, \omega_{\text{f}x} \in \mathcal{M}_{\text{B}B}\} \cup \{\omega_{\text{f}t}, \omega_{\text{f}t} \in \mathcal{M}_{\text{F}C}\}\
$$
(6)

174 where  $\omega_{fx}$  are backbone layers in which the weights are fixed for feature extraction while  $\omega_{ft}$  are weights of 175 the final fully connected layer updated for fine tuning. The weights update of fine tuning layers  $\mathcal{M}_{fc}$  follows <sup>176</sup> the learning objective deőned in Eq. 4 and 5 as to solve the same classiőcation problem.

#### 177 3.4 Mobile Application

 The approach described in Sec. 3.3 is suitable for use cases where the new image frames are unseen to the base model but are adapted through őne tuning to achieve the same learning objective. To assist with getting a more user-friendly interface of our proposed method, we take advantage of an Apple iPhone IOS based 181 app *Translitero* and port the pre-trained model weight  $\{\omega_{fx}, \omega_{ft}\}$  based on public hand-gesture dataset to the mobile end in Fig. 3, to provide the portability. The user interface allows the data collection process of the new use cases to be natural and fast.

<sup>184</sup> In Fig. 3 we sketch the core components that supports the őne tuning in a data-efficient manner:

<sup>185</sup> • Data Collection. The user interface opens up the camera to collect live video stream of the new <sup>186</sup> user's hand gesture for up to ten seconds. The user is prompted to make hand gestures of the 29 ASL <sup>187</sup> letters, and the recorded video clips are automatically labeled.

 • Fine Tune Backend. The collected data in video clips(MP4) are uploaded to a desktop computer server where a pipeline takes the RGB video frames and then follows the procedure detailed in Sec. 3.3 to optimize and obtain the őne tuned neural network weights. The őne-tuned neural network weights  $\omega_{ft}^{new}$  are then sent back to the mobile phone.

**• Live Inference.** The real-time video stream captured from mobile camera is projected to the handheld screen. In the meantime, the ASL model  $\{\omega_{\text{f}x}, \omega_{\text{f}t}^{new}\}\)$  takes the raw frames and predicts the most likely <sup>194</sup> ASL letter based on model inferences directly on the smartphone.

 The session time of data collection is set as one minute maximum per ASL letter. The collected video clip from iPhone device has the frame rate of 30Hz. As demonstrated in section 4, 10 seconds recording (∼300 frames) per ASL letter applied to model őne tune could attain an acceptable recognition accuracy, thus requiring less than 5 minutes recording time in total. It justiőes our proposed approach in realizing in-the-wild ASL recognition as well as the mobile user interface that provides a user-friendly and rapid data collection method.

## <sup>201</sup> 3.5 Implementation Details

<sup>202</sup> The őne-tuning method of ASL letter classiőcation, proposed in Sec. 3.2, is implemented under PyTorch <sup>203</sup> deep learning code framework [7]. The architectural details are below:

- Back Bone. Following the definition of  $M_{\text{B}B}$  in Equ. 3, we adopt MobileNetV2 [8] as the back bone architecture with pretrained weights that takes RGB image frames in size of 224 x 224.
- Classification. Following the definition of  $\mathcal{M}_{FC}$  in Equ. 3, the classification layer is a fully connected <sup>207</sup> (FC) one with dimension of 29 corresponds to the size of ASL letters introduced in this work.

208 For model training on  $M$ , we apply Adam optimizer [9] with the learning rate of 0.0005, and other optimizers. <sup>209</sup> A learning rate scheduler is also utilized during the training. The same optimization process is also adapted <sup>210</sup> for the model őne tuning.

<sup>211</sup> Translitero integrates multiple view controllers as the user interfaces developed in XCode 14.0 and IOS <sup>212</sup> 14.5 to satisfy data collection or online ASL inference. Portability of the ASL model is supported by LibTorch <sup>213</sup> 10.0 framework installed on an iPhone.



Table 1: ASL letter recognition accuracy in percentages. AA: results on ASL Alphabet dataset. TM: results on Translitero Mobile dataset.  $5/10/15$  seconds correspond to frame time length used for model fine tuning. The model fine tuning approach we proposed demonstrates the better accuracy.



Table 2: Ablation study of fine tuning based ASL letter recognition accuracy in percentage. Row 1-2: results of adapting different optimizers on model fine tuning under the same data collection time (10s); **Row** 3-4: results of applying image frames with blurred background but different data collection time during model fine tuning.



Figure 4: Visualization of ASL letter recognition qualitative examples. Column 1: ASL gesture frame samples captured from mobile camera using the app. **Column 2:** ASL letter recognition accuracy (bottomright red fonts) tested on pre-recorded ASL clips. Column 3: verification on recognition accuracy while applying virtual background to the clips. Row 1 and Row 2 correspond to ASL letters  $N$  and  $Z$ .

## 214 4 Experiments

 We have carried out ASL recognition experiments on teenager, adult and senior male and female hands in the wild and the accuracies obtained are compared.

## 4.1 Datasets

- <sup>218</sup> ASL Alphabet. The training data contains 87,000 images in 29 ASL letter categories, are 26 letters A-Z and 3 classes for SPACE, DELETE and NOTHING, which are necessary for spelling words and sentences.
- Translitero Mobile. Short-duration ASL alphabets video frames are captured using an iPhone. Those video clips are 1 minute in length containing 29 ASL letter categories to validate the model's ability of generalization.

 The ASL Alphabet dataset is further divided into training and testing splits for model learning and evaluation purposes. Video segments from the Translitero mobilephone-collected dataset are sampled in őxed length for model őne tuning and transfer learning. The rest of the video segments are used for evaluation. Variation of the sample video frame length used for őne tuning is discussed in Sec. 4.3

## 4.2 Methods

Among the various methods tested, the most effective methods for ASL letter recognition are:

**• Hand Geometry(HG).** This method extracts 3-D hand key points (landmarks) based on video image frames utilizing the Mediapipe [12] library. The geometry-based classiőer on 29 ASL letters are derived based on hand key points geometric relations.

- MobileNet ASL(MASL). The vanilla ASL classification model developed according to Sec. 3.2, 3.5 using public datasets with no customization. The model is trained end-to-end from image frames to 29 ASL classes upon ASL Alphabet dataset.
- **Fine Tuned MASL(MASL+FT).** The ASL classification model which uses the fine tuning technique (Sec. 3.3) using new individualized data from Translitero Mobile clip frames.

#### 4.3 Results

#### 4.3.1 Quantitative Results

 We summarize the quantitative results in Table 2 of the recognition accuracies evaluated on ASL Alphabet and Translitero datasets. The percentages are averaged over the 26 ASL letters A-Z. HG accuracies are all below 90% which indicates that the 3-D geometric cues extracted from hand key points are not precise enough to attain exceptional recognition accuracy. Results of MobileNet ASL(MASL) trained on ASL Alphabet dataset demonstrates the great performance if tested as well on the ASL Alphabet public dataset. However, the low recognition accuracies on Translitero Mobile dataset collected on new individuals indicates the model does not have the ability of generalization. During test time, a few of the ASL letters recognition accuracies are observed to be nearly zero. On the other hand, after employing the model őne tuning technique to MobileNet ASL model(MASL+FT), the issue of generalization gets largely mitigated. The 10s video frame length per ASL letter applied for fine tuning could achieve the test accuracy above 95%. Those quantitative results validate our transfer learning approach on improving performance of neural network models with high data efficiency.

#### 4.3.2 Qualitative Results

 In Fig 4, we selected two ASL letter recognition cases, "*N* " (row 1) and "*Z*" (row 2). The selected two cases are challenging according to our observations. Letter *N* is similar to *M* in appearance, with the only difference being in the position of the thumb tip relative to the őst. *Z* is a dynamic letter, which means that it involves the hand moving during the duration of the gesture. Since our modeling approach predicts per frame, there is a chance that the dynamic letters could suffer from lack of data. Despite that, most of our testing results showed 100% accuracies, which proves the quality when executing the őne tuned model.

#### 4.3.3 Ablation Study

 In machine learning, an ablation study is when we study the effects of parts of the model by removing or silencing certain layers. We conducted this type of study upon our őne tuned model to explore more alternatives that could obtain the optimal performance in terms of ASL letter recognition accuracy. In this work, we investigate the following variants:

**• Optimization Algorithm.** During the model fine tuning phase, the weights of fine tune layers,  $\omega_{tt}$ , are updated according to the gradient descent algorithm. Choices of optimization could result in different efficiency and accuracy.

<sup>267</sup> • Virtual Background. Considering the high background diversity of the video image frames captured on the mobile device, we additionally develop a functionality that enables attaching a customized background to the video stream. Inside the camera view, the background is blurred resulting in only

<sup>270</sup> the moving hands being visible. We apply this setup on both the őne-tuning data collection stage and 271 real-time ASL inference stage.

 In Table 2, among the listed optimization algorithms, the Adam optimizers [9, 11] attains better accuracy than RMSP [10]. And AdamW [11] could achieve the best accuracy given 10 seconds of őne-tuning data collection. Further, we observe that the ASL recognition accuracy is not having much performance change with various physical backgrounds (curtains, lighting, wallpaper) after applying the virtual background. For all the őne tuning collection time tested on 5, 10, 20 seconds, the accuracy results are close to the uniform background ones. Those are also demonstrated in the qualitative results in Fig. 4. These results prove the effectiveness of developing the virtual background feature in our mobile APP such that the impact of physical backgrounds to the ASL model could be mitigated to greatly enhance the usability.



Table 3: The above shows the hand gesture data collected from the mobile app. ASL finger spelling recognition was analyzed to assess the accuracy across categories of a teenage male, a teenage female, an adult male, an adult female, and a senior male. The accuracy is determined by the correct number of hand gesture predictions divided by the total frames, with the number of frame ranging from 80 to 123 depending on the device. The recognition system achieved high accuracy for teenage males and females as well as adult males and females. However, the accuracy is still less satisfactory for a senior male, likely due to factors such as hand tremors and variations in hand shape or size.

## <sup>280</sup> 5 CONCLUSIONS

 In conclusion, our research translates ASL to English with greater than 95% accuracy using only 2D video image-based inputs. The transfer learning method proved to be highly data-efficient during the training stage and was a lot more effective during testing due to its adaptiveness to different hands and environments. Furthermore, the mobile app with the transfer learning algorithm can be used in practical circumstances with different physical backgrounds that occur in real life. This could mean that ASL learning for the sign language community could be much easier in the future.

 The ASL algorithms and app may be further expanded into more areas. The app can be made to accommodate more than just the ASL alphabet, such as complete words. In addition, the sign language transfer learning method can be applied to more sign language systems such as the Spanish / French / Russian Sign Languages.

## <sup>291</sup> Acknowledgement

<sup>292</sup> We acknowledge the patient teaching and guidance by Mr. Yingchun Chen and Mr. James Ma.

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## 3rd Place Award

at the Massachusetts Science & Engineering Fair (MSEF) 2024

"Analysis and Machine Learning Modeling of Spatial Data to Identify Asthma Hotspots in Massachusetts"



# Analysis and Machine Learning Modeling of Spatial Data to Identify Asthma Hotspots in Massachusetts

Thomas Li, Weston High School

#### **BACKGROUND**

Asthma's uneven distribution across Massachusetts demonstrates a pressing public health issue, with specific areas experiencing disproportionately high rates of the condition. This disparity is often attributed to a complex interplay of environmental and socio-economic factors, underscoring the need for a detailed spatial analysis to identify asthma hotspots. This research is crucial for understanding the geographical nuances of asthma incidence, facilitating targeted interventions, and addressing environmental injustices that contribute to health disparities. Further, the rapidly evolving environment will mean that the current Asthma medical data will become quickly outdated.<br>
24-hour PM<sub>2</sub>, Excedance Days and Total Excedances 2013-2022





*2.5-micrometer Particulate Matter concentration exceedances per year. Demonstrates the unpredictable nature of environmental factors.* Massachusetts 2022 Air Quality Report(*https://www.mass.gov/doc/2022-annual-air-quality-report/download)*

#### QUESTION AND HYPOTHESIS

predictively generate the areas of Massachusetts that **Question:** Can machine learning models be used to are most prone to asthma?

**Hypothesis:** A Random Forest machine learning model can classify geographical locations as asthma hot spots with high accuracy based on environmental data.

#### REVIEW OF LITERATURE

Machine learning models have been extensively used to predict asthma exacerbations with various degrees of success. These models incorporate a range of predictors including demographic, clinical, and socioeconomic factors. The most commonly used machine learning algorithms are logistic regression and random forests, but other techniques like XGBoost and LightGBM are also in use. The number of predictors in these models can range widely from 1 to over 200, and they often include systemic steroids use, beta2-agonists, emergency department visits, age, and previous asthma exacerbation history. The performance of these models is quite variable, with the area under the receiver operating characteristic curve (AUROC) ranging from 0.59 to 0.90, indicating that while some models are excellent, others may have limited predictive power.

When focusing specifically on predictive models for asthma attacks, the use of biosignals and environmental factors is common. The majority of studies concentrate on biosignal risk factors, but a substantial number also factor in environmental triggers. The data acquisition methods for these models vary, including telemonitoring technologies, emergency department records, national databases, and environmental data from meteorological agencies and pollution monitoring stations. However, it's worth noting that having a large and varied population size is crucial for the reliability of the study's findings. The generalizability of these models is a challenge that requires further research across different groups and populations.

## METHODOLOGY CONCLUSIONS

# • We created a Random Forest model to predict

variety of publicly-available data.

hotspots is below:

**pediatric asthma hotspots in Massachusetts**, using a

• The final model was able predict whether a specific location was an asthma hotspot with **96.9% accuracy**. • The model suggests that the most critical Environmental factors for identifying geographical asthma hotspots are **distance to roads** and **particulate matter concentrations**, especially PM2.5. • The areas with the highest predicted asthma risk are the regions near **Springfield and Greater Boston.**  • The final interpolated map of predicted asthma

## **1) Aggregate data**

I collected as particulate matter concentration from MassDEP and pediatric asthma data from Massachusetts Environmental Public Health Tracking. 2021 AT Vontanna Network



#### **3) Build training set**

Randomly select spatial data points concentrated so that the areas with higher prevalence rates are equally represented



*Points from a random sampling of high asthma concentration areas and low asthma concentration areas. Made in ArcGIS Pro by studer* 

#### **4) Train ML model**

Train models using a variety of different hyperparameters and observe the resulting testing accuracies.



#### **5) Tune hyperparameters**

Experimented with hyperparameters min sample split, min sample leaf, n estimators, and max depth. Min Sample Split and Min Sample Leaf prevent overfitting by controlling node splitting and leaf size, ensuring trees don't learn the training data too precisely. N Estimators determines the forest's size, affecting accuracy and computation time. Max Depth limits tree complexity, helping avoid overfitting by restricting the number of decision layers. These hyperparameters collectively fine-tune the model's generalization and performance.



*Final training versus testing accuracies with the hyperparameters as the independent variable and the accuracy as the dependent variable. All other parameters are held constant.*

#### RESULTS

- The Random Forest model was able to predict whether a specific location was an asthma hotspot with **96.9% accuracy** and an **F1-score of 97.5%**.
- The highest accuracies were observed in models with 110 estimators, 15 max depth, 2.5 minimum sample split, and 2.5 minimum sample leaf.
- Of the various features tested, **distance to the nearest road** was the most important factor, with **PM2.5 levels** the next most important

#### **2) Interpolate spatial data**

Data collected using monitoring stations is only for a specific location. Therefore, we have to interpolate the monitored air quality onto the surrounding area.

We use the **Kriging interpolation** method in this instance, we use the Kriging interpolation method because of its ability to incorporate the spatial autocorrelation of the sampled data effectively. This method is particularly suitable for air quality data, which often exhibits strong spatial correlation. Kriging interpolation is a method that predicts values for unsampled points by utilizing the spatial correlation of the sampled data, as quantified by semivariance.



The variogram above is calculated from spatial data, showing how data similarity decreases with distance. Each point represents the semivariance between pairs of data points at a specific lag distance, revealing the spatial structure and continuity within the dataset. The pattern depicted by the points is used to model the variogram, which is fundamental for the Kriging interpolation process. This model helps in understanding the spatial correlation and is crucial for predicting values at unsampled locations with greater accuracy.



*Resulting interpolation maps for Asthma prevalence and PM 2.5 levels displayed in ArcGIS Pro and made by student.*

#### • Building a website or app that displays the hotspots in real time, so the results can be more easily accessible to the public. **API Backend Server Data Preprocessing Machine Learning Model Frontend Application User**

• Enriching the training dataset using additional features (such as ambient air temperature, average household income, demographic information, etc.), as well as additional historical data.

FUTURE WORK

• This model can be used to help public policy experts, families, and especially children **identify areas of high asthma** risk, with the goal of aiding prevention and

Areas of further research could include: • Predicting asthma hotspots for the current year.

treatment efforts.

**BRID** Very Li

**Data Ingestion** 

• Training additional models and fine-tuning to further improve results.

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**Thomas Li <25lit@weston.org>**

## **2024 Simons Summer Research Program at Stony Brook University - Thomas Li**

#### **Simons SRP** <simonssrp@stonybrook.edu> Tue, Mar 19, 2024 at 6:15 PM

To: Thomas Li <25lit@weston.org> Cc: Alisa Yurovsky <alisa.yurovsky@stonybrook.edu>, Alisa.Yurovsky@stonybrookmedicine.edu, Karen Kernan <karen.kernan@stonybrook.edu>

#### Thomas,

I am delighted to inform you that you have been admitted to the **2024 Simons Summer Research Program** based on the quality of your application, your strong academic record and the recommendations of your teachers. The Simons applicants include some of the best science students from all over the country. Your nomination by your high school for this fellowship is in itself an honor and an indication of your exceptional promise. And we have no doubt that you will make the most of this opportunity.

The Simons Summer Research Fellowship Program runs from **July 1st through August 9th, 2024**. During this time you will be working under the mentorship of Dr. **Alisa Yurovsky** in the Department of Biomedical Informatics. In addition to your research, you will be expected to attend all Simons Program activities, such as weekly lunches/informal research talks; and will be presenting at the closing poster symposium on August 9th. Upon successful completion of the program, all participants will be awarded a stipend of \$500 (which will be issued by check and sent via postal mail) after program has concluded.

#### **What you need to do next:**

*\*\*\*Please send an email to [SimonsSRP@stonybrook.edu](mailto:SimonsSRP@stonybrook.edu) by April 5th indicating whether or not you plan to accept the offer and participate in our program.* Should you decline the offer for any reason, we may be able to extend an offer to another student who would like the opportunity to participate in our program. If you accept the offer to participate in the 2024 Simons SRP program, we will send you additional information & forms in the following weeks.

If you have any questions at all, please do not hesitate to contact us. On behalf of Stony Brook University and all the faculty who served on our selection committee, we extend our congratulations to you, and look forward to meeting and working with you this summer.

sincerely, Karen Kernan, Director Simons Summer Research Program

--

**Simons Summer Research Program Stony Brook Union Suite 111-06, Stony Brook University Stony Brook, New York 11794-3257 tel: (631) 632-7114 / fax: (631) 632-4525 Email:** [SimonsSRP@stonybrook.edu](mailto:SimonsSRP@stonybrook.edu) [karen.kernan@stonybrook.edu](mailto:karen.kernan@stonybrook.edu) **Simons Webpage:** [http://www.stonybrook.edu//simons](http://www.stonybrook.edu/commcms/simons/index.html)



## Characterizing Machine Learning Methods for Medical Time Series Diagnosis

Thomas Li  $^{1,2}$ , Alisa Yurovsky  $^1$ 

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#### Abstract

Time Series data for medical information has the potential to revolutionize medical diagnosis by predicting diseases such as acute kidney failure months before they get diagnosed. However, current methods of doing this suffer from issues such as noisiness. This project uses the Trinetx dataset to characterize eGFR (Estimated Glomerular Filtration Rate) data, perform data imputation, test the performance of simple models as a function of the prediction range, and test time series transformer models and their performance. Data imputation was able to increase model performance by up to 3% in terms of the F1 score, and the models were able to obtain high accuracy for prediction ranges of up to 3 years. Further, transformer models were able to demonstrate effectiveness at classification tasks.

#### Introduction

Advances in AI have shown promise in improving early disease detection, yet challenges remain, particularly in analyzing medical time series data like eGFR and glucose screenings from EHRs. These data are often noisy, lack interpretability, and exhibit demographicspecific distributions. Our project focuses on characterizing the distribution of the data, identifying viable prediction time ranges, addressing data disparities, improving performance through imputation, and testing transformer models on medical time series data. By leveraging these models, we aim to facilitate earlier interventions and better healthcare outcomes.



*Figure 1: a) eGFR measurements for a healthy patient b) eGFR mea* up to AKF diagnosi.

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#### METHODOLOGY RESULTS

#### **1) Characterize Data Distribution**



#### **3) Simple Model Testing**

Train simple models such as Random Forest, KNN, and XG Boost and test their performance.





#### •eGFR time series data is divided into fixed-length patches.

•Patches are converted into embeddings with added positional encodings to retain temporal information. •Utilizes self-attention mechanisms to capture dependencies between different time patches. •Multiple encoder layers process the embeddings to create a comprehensive feature representation. •The pooled output embeddings are passed through a fully connected layer.

•The output layer classifies the time series data into the appropriate category (e.g., acute kidney failure). •Cross-entropy loss is used for classification. •Optimized with Adam optimizer



#### Characterized the distributions of both the negative dataset and positive dataset. **2) Data Filtering and Imputation**

Data was filtered by removing patients with a low number of lab results, filtering the months such that only results before the diagnosis date are kept, and removing / imputing outliers and invalid values. Various imputation methods were used such as KNN imputation, linear interpolation, mean imputation, and spline interpolation.



*Figure 3: Lab result filtering past a certain date to simulate diagnosing 3 months ahead.*



## Training and Validation Loss - Training Loss oss  $0.87$  $0.60$  $0.58$ 0.56  $0.54$ Enzylis

*Figure 6:. Validation and training loss plot for Patch Time Series Transformer*

- Imputation methods such as KNN performed with 2- 3% increased f1 scores.
- 5% drop in f1 score due to increased time range predictions.
- Transformers have a similar f1 score to other simple models of ~70%



#### **DISCUSSION**

- The relatively low drop in performance from increasing the time range suggests that the current models are not complex enough to capture all the time series information.
- The substantial improvement from imputation could lead to significant benefits for larger models, especially when applied to various datasets.
- Data imputation helps equal the distributions for negative and positive datasets and thus increases the training dataset by a large proportion.

#### FUTURE WORK

- Integrate various lab tests (e.g., glucose levels, blood pressure) to enhance prediction accuracy.
- Vision Time Series Transformers (ViTST) may be used to increase performance.
- Expand focus to include early detection of diseases like heart disease, diabetes, and chronic kidney disease.
- Develop demographic-specific models to improve robustness and reduce biases.
- Utilize self-supervised learning on extensive EHR data to create a comprehensive foundation model.
- Enhance interpretability by refining shapeletbased methods and validating them with clinical studies.



## **FW: Laboratory Learning Program - Acceptance email for -Thomas Li**

**Lab Learning Program** <lab-learning@princeton.edu> Tue, Apr 16, 2024 at 4:15 PM To: "dbbested@gmail.com" <dbbested@gmail.com>

Cc: "Z. Jason Ren" <zjren@princeton.edu>, "Moira J. Selinka" <mselinka@princeton.edu>, Junjie Zhu <junjiez@princeton.edu>, "liju@mit.edu" <liju@mit.edu>, Lab Learning Program <lab-learning@princeton.edu>

Dear Thomas,

Congratulations! We are pleased to inform you that you have been selected for the following opportunity in the Laboratory Learning Program. Participants often find that the research experience in the Laboratory Learning Program is transformative and very useful in choosing a field of study as they enter college. In this independent research opportunity, the educational benefit is closely linked to each individual's level of intellectual commitment and effort. This unique experience will allow you to be part of a world-class research endeavor.

Name of research project: ACEE-03, Large Language Model Applications in Environmental Sustainability Faculty mentor: Jason Ren Faculty email: [zjren@princeton.edu](mailto:zjren@princeton.edu) Department manager: Moira Selinka Department manager email: [mselinka@princeton.edu](mailto:mselinka@princeton.edu) Department manager phone number: 609-258-8456 Lab training: Not required

To successfully enter you into the program, please complete & submit the forms on this webpage [https://scienceoutreach.princeton.edu/laboratory-learning-program-information-accepted-students](https://scienceoutreach.princeton.edu/laboratory-learning-program-information-accepted-students-and-parentsguardians)[and-parentsguardians](https://scienceoutreach.princeton.edu/laboratory-learning-program-information-accepted-students-and-parentsguardians) to FACULTY, DEPT MANAGER, **SUPERVISING** STAFF, LLP emails by **April 26, 2024.** 

Please connect with the researchers and department manager to arrange the participation details (for example, dates, daily hours, training).

All student participants must submit a non-confidential minimum 2-page project summary by August 20, 2024, or upon completion of the research project.

The Laboratory Learning Program **does not include** housing, transportation, social activities, or entertainment. There is no supervision provided beyond the research-related activities. Be advised that LLP students are not eligible for University housing (lease or sublease). Whether you live locally or outside of the immediate area, parents/guardians are solely responsible for safe and appropriate housing/transportation arrangements.

**Faculty/department managers**: if the student is not local, you need to verify they have local accommodation with a responsible adult (confirm contact information).

Sincerely,

## **Dr. Paryn A. Wallace** Associate Director of Science Outreach

## **Lynne Brown**

Office Manager, Environmental Health & Safety

Laboratory Learning Program [lab-learning@princeton.edu](mailto:lab-learning@princeton.edu)

CC: Faculty Department Manager Supervising lab member Parent

# **Princeton Laboratory Learning Program Report**

**Thomas Li, August 16, 2024** 

# **Introduction**

The growing need for accurate and comprehensive data on greenhouse gas emissions from wastewater treatment facilities has never been more pressing. As the world grapples with the challenges of climate change, the role of water resource recovery facilities (WRRFs) in both contributing to and mitigating emissions has gained significant attention. However, existing protocols, such as those outlined by the IPCC, often rely on emission factors and variables that lead to inaccuracies, including the overestimation of nitrous oxide  $(N_2O)$  and underestimation of methane  $(CH_4)$  emissions. Addressing these gaps requires a comprehensive approach. We need to collect data for each wastewater treatment facility, including detailed operational parameters, process inputs, and corresponding emissions data. However, gathering the initial preexisting information for each facility can be a daunting task. This is where the web scraper, integrated with a large language model (LLM), comes into play. We want to test the hypothesis that it is possible to gather information on wastewater treatment facilities using an LLM-based web scraper. It will gather and synthesize information on wastewater treatment facilities across the United States and lay the groundwork for a more accurate inventory of emissions within this sector. There are various types of data that need to be collected for each facility. These include publicly available greenhouse gas emissions data, contact information, net zero by 2050 plan, whether the region's greenhouse gas inventory features wastewater, and whether the region's climate action plan features wastewater.

# **Methodology**

The scraper is composed of three parts **—** a content finder, an interpreter, and an LLM.



**Figure 1**. Displays the methodology of the scraper.

The content finder is made using the Selenium library. It searches and filters content until it finds web pages suitable for the question. Then, the web page is fed to the interpreter, which turns the web page into suitable text that LLM can read. Different types of searches typically find other forms of web pages, so the interpreter needs to be flexible in accounting. The LLM may occasionally call back to the content finder to view a link on the web page. The system is called over every facility for specific questions.

## **Data**





The web scraper fulfilled all tasks except finding publicly available greenhouse gas inventories.

# **Conclusion**

We successfully created a web scraper that utilizes LLMs to find information on Wastewater Treatment Facilities. However, we need help finding data for more hidden information, such as public greenhouse gas inventories. This either shows the limitations of such methods or that such data does not exist in the public domain, and helps motivate the greater project.

# **Acknowledgment**

I am so grateful for the support and guidance of Prof. Jason Ren and Emily Mayo. During this period, I have learned a lot, especially about the processes involved with wastewater treatment and environmental contaminants.

# ™**ACT**

## ◆ ACT Test Admission Ticket

A You must bring a printed copy of this page. We do not accept it on mobile devices.

### Li, Thomas C Jan. 17, 2007



## **ACT Test**

Sunday Feb. 07, 2021, 8:00 am **BROOKLINE HIGH SCHOOL** (code 220361) MAIN BUILDING, 1ST FLOOR ROOM 147 115 GREENOUGH ST **BROOKLINE, MA 02445** 

Hi Thomas! This is your ACT Test Admission Ticket. On test day, bring acceptable photo ID\*, a printout of this page, and other items listed below. To make any changes, sign in at myact.org. Thanks and good luck!

SEATING ASSIGNMENTS ARE POSTED IN FRONT OF BROOKLINE HIGH SCHOOL. FIND YOUR SEATING ASSIGNMENT OUTSIDE BEFORE **ENTERING THE BUILDING.** 



#### Test Day Policies

- You must be at your test center by 8:00  $am$
- You cannot handle or activate any electronic device (including phones, smart watches and fitness watches) from test room admittance until dismissal, including breaks.
- of If there's severe weather, check act.org/alerts or local radio and TV.
- Ÿ You'll probably be done testing in 5-6 hours.

#### In What to Bring

- 1. Acceptable photo ID\*
- 2. Paper printout of this page
- 3. Pencils: sharpened #2 lead with good erasers
- 4. Permitted calculator for use only on the math section. It is your responsibility to know whether your calculator is permitted. To find out, see act.org/calc or call 800-498-6481 for a prerecorded message.
- 5. A watch (but no smart watches or watch fitness bands) to pace yourself.
- 6. Snack to eat outside the test room on break.

#### ⊘ What Not to Bring

- ⊘ ANY electronic device other than a permitted calculator.
- **⊘** Highlighters, correction fluid, colored pencils, or other aids.
- **Ø** Textbooks, foreign language or other dictionaries, scratch paper, notes or other aids or reading material.
- **Ø** Tobacco of any form.

**A** Test Day Match Info: On your test day answer document, you must enter this data exactly as it appears below:

- $\overline{B}$ Match Name (1st 5 letters): LI
- $\mathsf{C}$ Match Number: 00601-40901
- Date of Birth: JAN 17 07  $\mathsf D$

#### **\*** Acceptable ID Requirements

To test, you must bring one of these forms of ID. The name on the ID must match the name shown above on this ticket.

- Original, current official government-issued photo ID
- Current School ID in hard plastic-card format
- Otherwise, print an ACT Student ID Form at act.org/studentid
- Talent Search students only: Use the ACT Talent Search ID Form provided with this ticket.

**@ Need Help?** 

## **Thomas's ACT Scores**



#### **Need Help?**

See [FAQs \(./support/\)](https://my.act.org/support/) or [Contact us \(https://www.act.org/content/act/en/products-and-services/the-act/the-act-test-contact-us.html\).](https://www.act.org/content/act/en/products-and-services/the-act/the-act-test-contact-us.html) [Home](javascript:void(0);) [Register/Buy... \(./products\)](https://my.act.org/products) [Careers, Colleges, & Majors \(./plans\)](https://my.act.org/plans) [My Account \(./profile/account-information\)](https://my.act.org/profile/account-information)

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Weston High School<br>444 Wellesley St., Weston, MA 02493 Tel: (781) 786-5800, Fax: (781) 786-5829 School CEEB Code: 222355

## **Transcript**

#### Courses Taken 2021-2022 Grade 09



## Courses Taken 2022-2023 Grade 10



# Li, Thomas Cheng<br>11 Wildwood Ln, Weston, MA 02493

Page 1 of 1

Days

Absent

 $1.0$ 

8.0



#### Courses Taken 2023-2024 Grade 11



**Attendance** 

#### **High School Credit Summary**



#### Codes for courses in which a standard letter grade is not earned:

 ${\sf N}$ 

- $= Pass$  $M = Medical$
- $=$  Incomplete
- $W = Withdrawal$

P

= Minimum attendance requirements not met



Please see the Curriculum Notes for descriptions of courses and levels.

Date Generated: 06/24/2024



## Weston High School Academic Year 2024-25

444 Wellesley Street, Weston, MA 02493

Main Office (781) 786-5800

## **Student Number: 30272**

Li, Thomas

Grade: 12

## 2024-25 Course List





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# Student Score Report

## **Report Date:**  10/01/2024



**AP ID/AP Number: W27V17UY** 

## School: 222355 - Weston High School



2024 AP Scholar with Distinction

2023 AP Scholar



The Commonwealth of Massachusetts<br>House of Representatives<br>State House, Boston 02133-1054

ALICE H. PEISCH **REPRESENTATIVE** 14TH NORFOLK DISTRICT WELLESLEY - WESTON - LINCOLN ASSISTANT MAJORITY LEADER

STATE HOUSE, ROOM 234 TEL. (617) 722-2783 Alice.Peisch@MAhouse.gov

February 2, 2024

Thomas Li 444 Wellesley Street Weston, MA 02493

Dear Mr. Li:

I write to congratulate you on placing first in the Platinum and Gold Divisions, at the nation's largest cyber defense contest, the Cyberpatriot's National Youth Cyber Defense Competition. This is a significant achievement, acknowledging your cybersecurity skills and your ability to perform under pressure. You have demonstrated strong leadership communication and cooperation skills throughout this program.

Again, congratulations, and please do not hesitate to contact me in the future if I can ever be of any assistance.

Very truly yours,

**ALICE HANLON PEISCH State Representative** 14<sup>th</sup> Norfolk District



## **EDIT ACCOUNT DETAILS**

If you identify as female, you can be among those considered for selection as a finalist to train for the USA team attending the European Girls Olympiad in Informatics (EGOI), assuming you also list USA as your country. If this is the case, please indicate below that you are EGOI eligible.





# Your Scores



# Career Insights Snapshot

Your skills are in demand! Consider exploring these growing careers in your state that need skills like yours. **These are examples, not recommendations**, to help jump-start your career exploration.



\*For more information about career insights, including interest areas, visit **[satsuite.org/whatsnext](https://reporter-prod.scoredelivery-prod.collegeboard.org/reports/satsuite.org/whatsnext)**.

\*\*Number reflects the expected number of new job openings in 2028. Percentage reflects the expected growth in new job openings between 2023 and 2028. *Data source: Lightcast.io*



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**satsuite.org/whatsnext**

## **Byte Size Arxiv Project** Sep. 2022 - Dec. 2022 https://bytesizearxiv.com

• Led a team of 5 college undergraduate and high school students to algorithmically summarize millions of academic papers from Cornell's Arxiv.org database, using machine learning and term frequency identification.

• Developed a database and website to automatically summarize and post a bulleted description each time a new paper is published on Arxiv, leveraging recent advancements in Large Language Models and GPT.

• Organized weekly meetings to cover progress and agenda for each week, including delegating tasks for coding the database, website, and search engine

# **Welcome to Byte Size Arxiv**

Papers made digestable

Here are some reccomended categories:

Browse Categories

## 2024-08-30

# **Signatures of polarized chiral spin disproportionation in rare earth nickelates**

Of several proposed mechanisms, here we test the hypothesis that pairs of self-doped ligand holes spatially condense to provide local spin moments that are antiferromagnetically coupled to Ni spins. These singlet-like states provide a basis for long-range bond and spiral spin order. These spin spirals are found to preferentially couple to X-ray helicity, establishing the presence of a hithertounobserved macroscopic chirality. Experimentally constrained theoretical double-cluster calculations confirm the presence of an energetically stable spin-disproportionated state with Zhang-Rice singlet-like combinations of Ni and ligand moments.

Read more →

## 2024-08-30

# **Performance Analysis of Pair-wise Symbol Detection in Uplink NOMA-ISaC Systems**

The results show that the derived expressions are perfectly matched with the simulation results.

Read more →

2024-08-30

# **Two-loop QCD corrections to Higgs radiative decay to vector quarkonium**

We calculate the two-loop QCD corrections to  $H\to J/\psi(\Upsilon)+\gamma$ using an optimized nonrelativistic QCD (NRQCD) approach. },  $\hat{H} \rightarrow \gamma^* \gamma$  followed by the virtual photon fragmentation into  $J/\psi$ .

Read more →

## 2024-08-30

# **Signatures of topology in generic transport measurements for Rarita-Schwinger-Weyl semimetals**

Furthermore, the final expressions turn out to be insensitive to the specific values of the chemical potential and the temperature. The second scenario involves computing the magnetoelectric conductivity under the action of collinear electric  $(E)$  and magnetic ( **B**) fields, representing a planar Hall set-up.

## Read more →

# 2024-08-30 **Positivity and Green's operators**

In this paper we investigate the matter of just how far from being positivity preserving a positive Green's operator can be. We will also identify a broad class of Green's operators that are not necessarily

positivity preserving but have properties related to positivity preservation that one expects from positivity preserving Green's operators.

Read more →

## 2024-08-30

# **Linear constellations in primes with arithmetic restrictions**

We prove analogues of the Green-Tao-Ziegler theorem on linear constellations in primes, in which the primes under consideration are restricted by certain arithmetic conditions. To illustrate this second result, we present an application in inverse Galois theory.

# Read more →

# 2024-08-30 **From free idempotent monoids to free multiplicatively idempotent rigs**

A multiplicatively idempotent rig (which we abbreviate to mirig) is a rig satisfying the equation  $r2 = r$ . We show that a free mirig on finitely many generators is finite and compute its size.

Read more →

2024-08-30

# **Quantum state testing with restricted measurements**

In practice, not all measurements can be easily applied, even using unentangled measurements where each copy is measured separately. Our work bridges this gap in the literature.

Read more →

FACULTY OF SCIENCE, DEPARTMENT OF PHYSICS

# CERTIFICATE OF DISTINCTION

2024 RECIPIENT

# Thomas Li

WHO, IN THE ANNUAL SIR ISAAC NEWTON EXAM, PLACED 133RD IN THE WORLD, OUT OF 3077 PARTICIPANTS AND 12TH IN UNITED STATES, OUT OF 86 PARTICIPANTS

ROGER MELKO Exam Coordinator, Sir Isaac Newton Exam School: Onphysics.Com And Greater Boston Chinese Cultural Association (Gbcca) Exam Date: May 2, <sup>2024</sup> Teacher: Xiaoliang Qin

